#### **POWER SUPPLY**

Separated 24 Vpc for logic (mandatory) and 12÷36 Vpc for power

H-bridge bipolar chopper of 40 KHz

#### **CURRENT**

 $0 \div 3.0 \text{ ARMS } (0 \div 4.2 \text{ APEAK})$ 

#### STEPLESS CONTROL TECHNOLOGY

65536 position per turn

#### CONTROL INTERFACES

Serial RS485 or CANbus and SCI interface for programming and real time debugging (not isolated)

#### INPUTS / OUTPUTS

- 4 digital inputs (not isolated)
- 3 digital outputs (not isolated) 1 analog input (potentiometer)

#### **DIRECT FEEDBACK INTERFACE**

5V TTL/CMOS or 24Vpc push-pull for incremental encoder (not isolated)

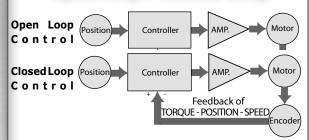
#### SAFETY PROTECTIONS

Over Current, over Temperature, closed Windings phase/phase phase/ground

#### TEMPERATURE

Operating from 5°C to 40°C, storage from -25°C to 55°C Humidity: 5%÷85% not condensed

## Open-loop-//Olosed-Loop



### • with regard to an Open Loop Stepper Solution:

- reliable positioning without synchronism loss:
- keeps the original position stable and recovers it automatically in case of positioning errors caused by external factors such as mechanical vibrations:
- 100% use of the motor torque;
- capacity to operate at high velocity related to the current control, which is adjusted depending on the load variations, where the normal systems in open loop use a constant current control at all velocities without considering the load variations.
- compared with a brushless servo controlled solution:
  - no need to adjust the power (automatic current regulation depending on the load changes);
  - keeping the position stable without fluctuations after completing the positioning;
  - quick positioning favoured by the independent control of the integrated DSP;
  - continuous and fast execution of short stroke movements thanks to the short positioning time.

## Full Digital Programmable Drive with fieldbus

## eteco besuben dillw lortmon noticell beautylly rol







# SB4D **Open frame**

- Multiform Control Modes
- On Board Safety provisions:
  - √ fully tested for direct installation unit
  - √ built in watch dog functionality
  - √ fault monitoring and handling
  - √ on field working errors buffering
  - √ separated power supply for logic and power
- Servomotors main features:
- $\sqrt{}$  Stepless control technology  $\sqrt{}$  PLC functionality
- √ low motor vibration
- √ closed loop
- √ low heat production
- √ high speed and torque
- √ no resonance
- √ high reliability



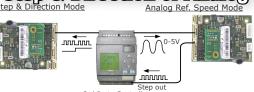
#### ELETTRONICA PER AUTOMAZIONE INDUSTRIALE

Via del Commercio, 2/4 -9/11 Loc. S. Grato - Z.I.

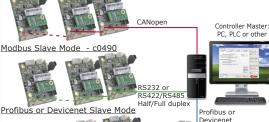
26900 - LODI (LO) - Italy Tel. 0039 0371 412318 - Fax 0039 0371 412367

email infoever@everelettronica.it www.everelettronica.it

## Sar-8-Plaston-or/\nalog









Up to 32 controllable drives thanks to the GWC Gateway unit

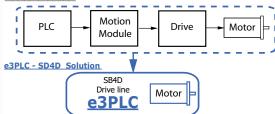
Drive control through commands by Master Controller. Suitable for multi axes systems (up to 127 drives). Built in Powerfull Motion Module functionality assures Perfect Synchronization among axes and reduces Master Controller workload

## Stand Alone Mode

#### User Programmable - eePLC- c0490

e3PLC integrates PLC, Motion Module, Process Module and drive in One Device. e3PLC Studio PC interface is available to friendly, fast and easy custom to machine or process device programming.

#### **Traditional Solution**



e3PLC Handler allows user to access all the functionalities and resources of the device and to manage and synchronize the motion module and other drive resources to any process' events.

Access to all Powerful Motion functionalities

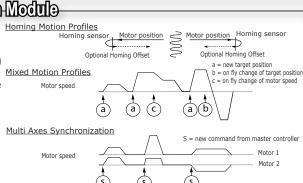
Built in **Process Real Time Modules** for special applications:

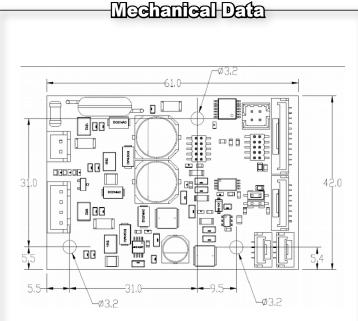
- Labelling
- Labelling Premium
- CAM
- Wire Processing
- User Custom Process



## Power Motton Module

- Step & Direction Control Mode
- Velocity Control Mode
- Wide range of Positioning Control Modes (homing, relative, absolute, target)
- CAM Mode... cam profile can be programmed
- Electric Gear with programmable gear ratio to track external master reference (from fieldbus or incremental encoder) of motor Speed and Position
- High speed I/O triggered motor start & stop to event syncronizing for fast response demanding application: labeling, nick\_finder, on fly cut., etc ...
- Multi Axis movements syncronization capability
- On fly change among any Motion Module Control Modes
- On fly Electric Gear Enable/Disable capability
- Motor Stall detection & Target Position tracking through encoder feedback





Ordering information of SE4D open frame drives and options

Order co	Power			System Resources								
Versions	Config. (see table)	Power su Power	pply Logic	Current	CAN	Serial	Dip-switches settings mode	SCI	Digital Inputs	Digital Outputs	Analog Inputs	Encoder interface
SB4D2030C2E1-30	c0380 c0390	· 12 ÷ 36 Vdc	24 Vdc	0 ÷ 3,0 Arms (0 ÷ 4,2 Apeak)	CANbus (Canopen)		None: the NodeID and the Baud Rate of interface is settable only in software mode	For configuration and/or 4		3	1	1 5V TTL/CMOS or 24 Vcc Push-Pull
SB4D2030C2E1-31							8 dip-switches to set the NodeID and the Baud Rate of interface also in hardware mode					
SB4D2030M2E1-30	c0490					RS485 (Modbus)	None: the NodeID and the Baud Rate of interface is settable only in software mode		· '			
SB4D2030M2E1-31							8 dip-switches to set the NodeID and the Baud Rate of interface also in hardware mode					

Configuration, Control Method and Optional Software Starter Kits									
Config.	Control	Software Starter Kits Code	Description of the Software Starter Kits						
c0380	Canopen Control Mode (CiA DS402 profile)	SW4_SERV00-SL	Communication kit for SCI service interface to configure the drive with Ever Studio.						
c0390	Stand-Alone e3PLC Studio IDE Canopen Mode	SW4_SERV00-EE	Communication kit for SCI service interface to program the drive with e3PLC Studio IDE.						
c0490	Stand Alone e3PLC Studio IDE Modbus RTU Mode	SW4_SERV00-EE	Communication kit for SCI service interface to program the drive with e3PLC Studio IDE.						