

Installation instructions

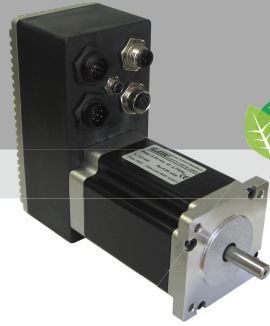


Refer to installation use and maintenance manual for more information.



Bipolar drive integrated with 2 phase step motor

- AC power Supply: 18 ± 56Vac;
- DC Logic Supply: 24Vdc (optional);
- Phase current : up to 4,2 ARMS (6 APK);
- Chopper frequency: ultrasonic 40KHz;
- Stepless Control Technology (65536 position per turn);
- Protections: over-current, over-temperature, short circuit phase-phase motor and phase-ground;
- Modbus or Canbus communication interfaces;
- Service SCI interface for programming and real time debugging;
- Digital inputs (opto-coupled);
- Digital outputs (opto-coupled);
- Analog input (opto-coupled);
- Size and mass: Length (mm)x124x60mm. Connectors not included(L x D x H : refer to picture);
- IP protection: IP65;
- Working temperature 5°C + 40°C ; Storage temperature -25°C + 55°C ;
- Humidity : 5% + 85% not condensing;



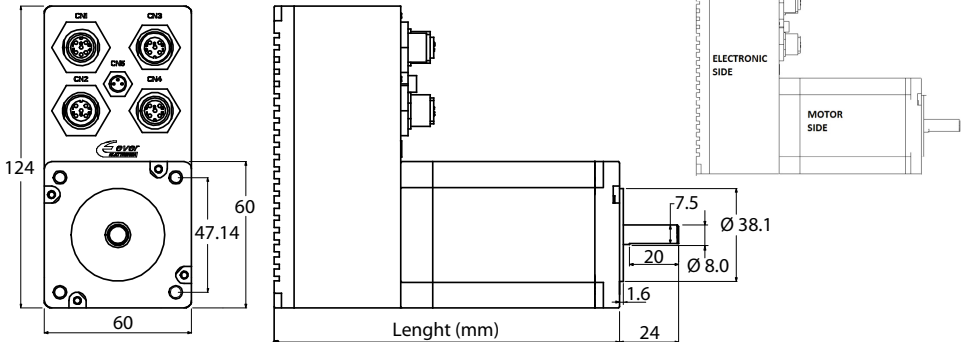
Mechanical data



Handle systems with care by taking them from the motor side and not from the electronics side.

Shaft axial load = 15 N max

Shaft radial load = 75 N max (on front shaft end)



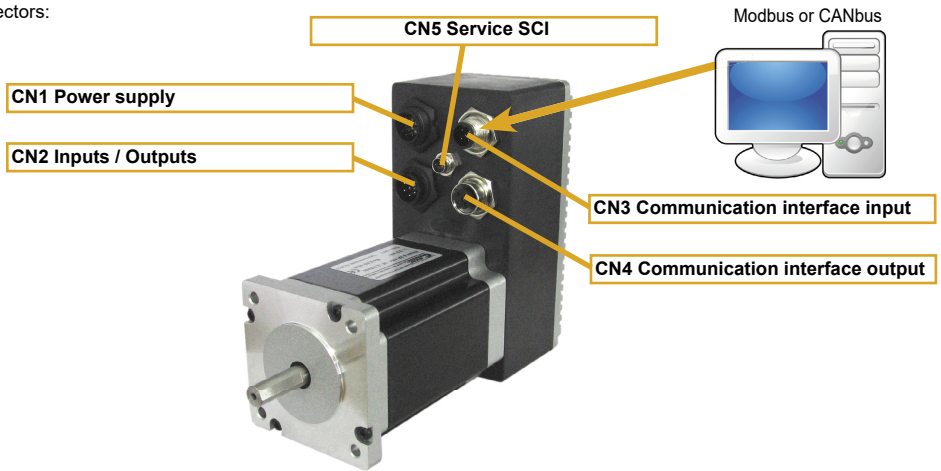
| | | | | | | | | | | |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|
| Composition code | SM4A | 3 | 42P | x | 2 | y | 2 | z | w | 0 |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|

| Model (z letter) | Length (mm) | Shaft Ø (mm) | D-cut on shaft (mm) | Holding Torque (Nm) | Rotor Inertia (g.cm ²) |
|--------------------|-------------|--------------|---------------------|---------------------|------------------------------------|
| SM4A342P_2_2_2_0 | 100.5 | 8.0 | 7.5 x 20 | 1.1 | 275 |
| SM4A342P_2_2_2_C_0 | 110.5 | 8.0 | 7.5 x 20 | 1.65 | 300 |
| SM4A342P_2_2_2_D_0 | 120.5 | 8.0 | 7.5 x 20 | 2.1 | 570 |
| SM4A342P_2_2_2_E_0 | 140.5 | 8.0 | 7.5 x 20 | 3.3 | 840 |

| Model (w letter) | Incremental Encoder (ppr) |
|--------------------|---------------------------|
| SM4A342P_2_2_2_N_0 | Without encoder |
| SM4A342P_2_2_2_4_0 | 400 |
| SM4A342P_2_2_2_5_0 | 1000 |
| SM4A342P_2_2_2_6_0 | 2000 |

System connections

Connectors:



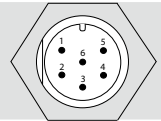
- Power and Logic supplies are not isolated but they have common reference inside the drive.**
- Use two separate and isolated supply for logic and digital outputs.**
- Connect GND of the logic supply and VSS of the output supply to PE near to the origin of the supplies with two different wires.**
- Do not connect simultaneously PE to the secondary circuit of the power transformer and to GND of the logic supply, otherwise the drive breaks and becomes unusable.**

| | | | | | | | | | | |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|
| Composition code | SM4A | 3 | 42P | x | 2 | y | 2 | z | w | 0 |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|

CN1 Power supply

| | | | |
|-------|--------|--------|---|
| CN1.1 | AC in | PWR_IN | AC power supply 18 ÷ 56 Vac |
| CN1.2 | AC in | PWR_IN | AC power supply 18 ÷ 56 Vac |
| CN1.3 | PE | EARTH | Protective Earth |
| CN1.4 | n.c. | --- | Not connected |
| CN1.5 | + Vlog | PWR_IN | Positive logic supply input +24 Vdc (optional) |
| CN1.6 | - Vlog | PWR_IN | Negative logic supply input GND (optional) |

Connector
 Type: screw, 6 pins, male, IP67
 Manufacturer: LTW
 Model: LTWBDD-06PMMS-SC7001

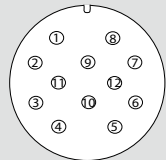


CN2 Inputs and outputs

y = 4 : 4 digital inputs and 2 digital outputs

| | | | |
|--------|---------|---------|---|
| CN2.1 | +B0_IN0 | DIG_IN | Digital input positive side |
| CN2.2 | -B0_IN0 | DIG_IN | Digital input negative side |
| CN2.3 | +B0_IN1 | DIG_IN | Digital input positive side |
| CN2.4 | -B0_IN1 | DIG_IN | Digital input negative side |
| CN2.5 | +B0_IN2 | DIG_IN | Digital input positive side |
| CN2.6 | -B0_IN2 | DIG_IN | Digital input negative side |
| CN2.7 | +B0_IN3 | DIG_IN | Digital input positive side |
| CN2.8 | -B0_IN3 | DIG_IN | Digital input negative side |
| CN2.9 | B0_OUT0 | DIG_OUT | PNP digital output OUT0 |
| CN2.10 | B0_OUT1 | DIG_OUT | PNP digital output OUT1 |
| CN2.11 | +24 V | PWR_IN | Input positive power supply digital outputs |
| CN2.12 | VSS | PWR_IN | Negative reference power supply digital outputs |

Connector
 Type: 12 pins panel rear mount screw type, male, IP67
 Manufacturer: LTW
 Model: LTWBU-12PMMS-SC7001



y = 7 : 4 digital inputs, 2 digital outputs and 1 analog input

| | | | |
|--------|---------|---------|---|
| CN2.1 | +B0_IN0 | DIG_IN | Digital input positive side |
| CN2.2 | +IN_AN0 | AN_IN | Analog input positive side |
| CN2.3 | +B0_IN1 | DIG_IN | Digital input positive side |
| CN2.4 | -IN_AN0 | AN_IN | Analog input negative side |
| CN2.5 | +B0_IN2 | DIG_IN | Digital input positive side |
| CN2.6 | V_POT | PWR_OUT | Voltage supply for potentiometer |
| CN2.7 | +B0_IN3 | DIG_IN | Digital input positive side |
| CN2.8 | COM_IN | PWR_IN | Reference digital inputs and outputs |
| CN2.9 | AGND | PWR_OUT | Output negative reference for potentiometer |
| CN2.10 | B0_OUT0 | DIG_OUT | PNP digital output OUT0 |
| CN2.11 | B0_OUT1 | DIG_OUT | PNP digital output OUT1 |
| CN2.12 | +24V | PWR_IN | Input positive power supply digital outputs |

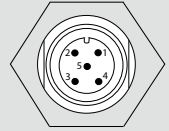
System connections

| | | | | | | | | | | |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|
| Composition code | SM4A | 3 | 42P | x | 2 | y | 2 | z | w | 0 |
|------------------|-------------|----------|------------|----------|----------|----------|----------|----------|----------|----------|

CN3 Communication interface input

| x = C : CANbus | | | |
|----------------------|---------|-------------|----------------------------|
| CN3.1 | n.c. | --- | Not connected |
| CN3.2 | n.c. | --- | Not connected |
| CN3.3 | CAN_GND | PWR output | Signal ground |
| CN3.4 | CAN_H | Digital I/O | Bus Line High |
| CN3.5 | CAN_L | Digital I/O | Bus Line Low |
| x = M : Modbus RS485 | | | |
| CN3.1 | n.c. | --- | Not connected |
| CN3.2 | n.c. | --- | Not connected |
| CN3.3 | 0V_A | PWR output | Signal ground |
| CN3.4 | Data + | Digital I/O | Not inverting signal RS485 |
| CN3.5 | Data - | Digital I/O | Inverting signal RS485 |

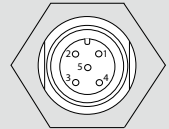
Connector
Type: M12, 5 pins, male, IP68
Manufacturer: LTW
Model: LTW1205-05PMMS-SF8001



CN4 Communication interface output

| x = C : CANbus | | | |
|----------------------|---------|-------------|----------------------------|
| CN4.1 | n.c. | --- | Not connected |
| CN4.2 | n.c. | --- | Not connected |
| CN4.3 | CAN_GND | PWR output | Signal ground |
| CN4.4 | CAN_H | Digital I/O | Bus Line High |
| CN4.5 | CAN_L | Digital I/O | Bus Line Low |
| x = M : Modbus RS485 | | | |
| CN4.1 | n.c. | --- | Not connected |
| CN4.2 | n.c. | --- | Not connected |
| CN4.3 | 0V_A | PWR output | Signal ground |
| CN4.4 | Data + | Digital I/O | Not inverting signal RS485 |
| CN4.5 | Data - | Digital I/O | Inverting signal RS485 |

Connector
Type: M12, 5 pins, female, IP68
Manufacturer: LTW
Model: LTW1205-05PFFS-SF8001



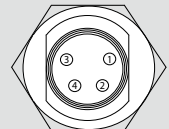
CN5 Service SCI interface

| x = C : CANbus | | | |
|----------------|---------|-------------|---------------------------------------|
| CN5.1 | GND | PWR_OUT | GND power output |
| CN5.2 | +5E | PWR_OUT | +5V power output |
| CN5.3 | DE / RE | DIG_OUT | Drive enable negated / Receive enable |
| CN5.4 | TX / RX | Digital I/O | Transmit / Receive line |



This connection is possible **only** with hardware and software provided by EVER Co.
 Kit code: **SM4A_SERVO-KIT**

Connector
Type: M12, 5 pins, female, IP68
Manufacturer: LTW
Model: LTW1205-05PFFS-SF8001



Digital inputs connection

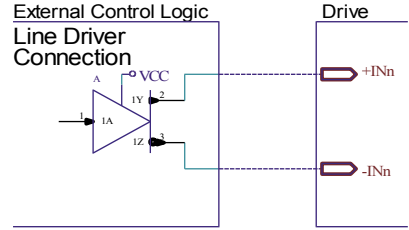
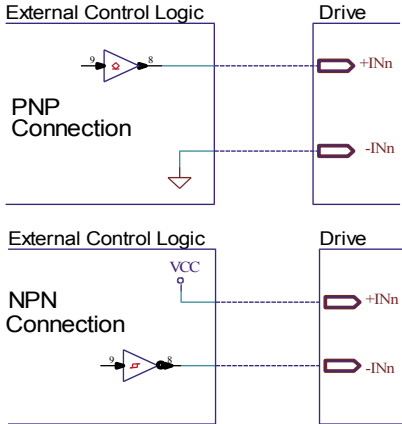
| | | | | | | | | | | |
|------------------|------|---|-----|---|---|---|---|---|---|---|
| Composition code | SM4A | 3 | 42P | x | 2 | y | 2 | z | w | 0 |
|------------------|------|---|-----|---|---|---|---|---|---|---|

i Differential PNP, NPN and Line Driver type or single-ended PNP type.

VERSION -----> y = 4

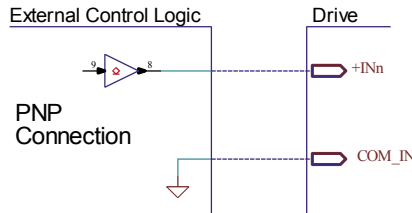
3.3 - 24V Differential

2 - 24V Differential



VERSION -----> y = 7

3.3 - 24V Single Ended



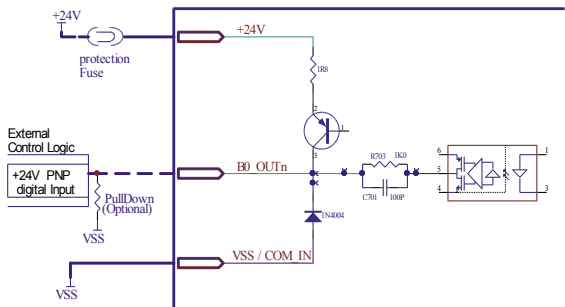
With single-ended configuration, digital inputs have common ground (COM_IN) with digital outputs.

Take this in consideration in the final installation.

N.B. It's recommended to use 2Vdc digital inputs only in Differential Line-Driver configuration to have more noise immunity.

Digital outputs connection

Digital outputs $V_{outmax} = 24Vdc$, $I_{outmax} = 100mA$

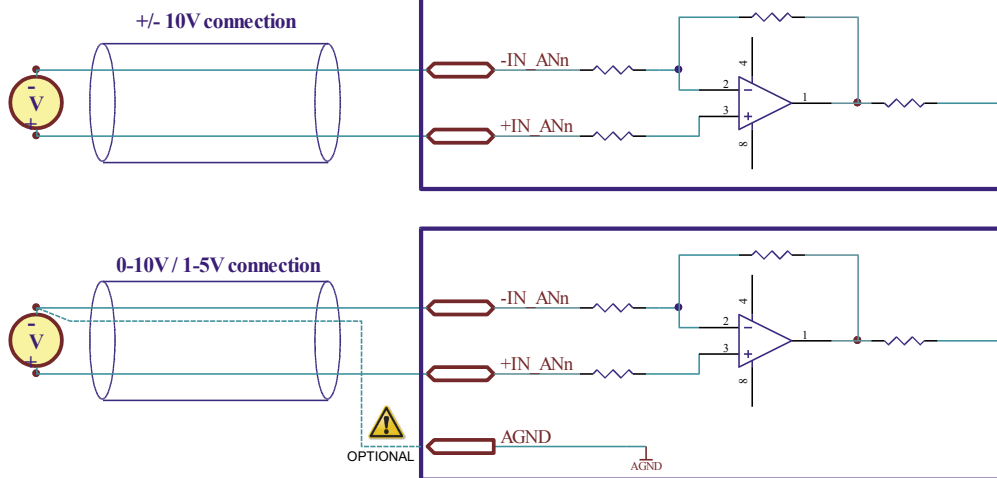


Analog input connection



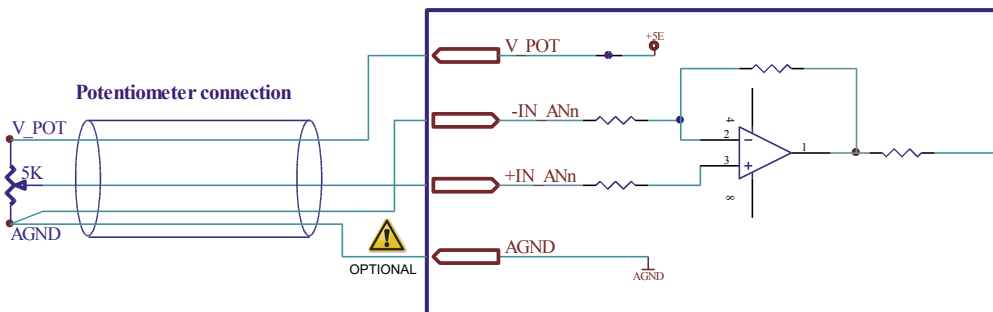
The resolution of the analog input depends from the type of the connection which could be defined by software: differential or potentiometer.

Differential connection



The connection from an external reference and AGND should be preceded by a thorough risk analysis on the machine/circuit in which the drive will be installed.

Potentiometer connection



AGND is internally in common with power ground, this is potentially dangerous. Take all necessary measures to avoid possible contacts in the final installation.

Mating cable kit

| Connection | Connector kit information | | Kit order code |
|------------|--|---|--|
| CN1 | Pin: Pinout: Conductors: Cable: Waterproof rate: | 6 position 1 - Blue, 2 - Green, 3 - Yellow, 4 - Orange, 5 - Red, 6 - White. UL2464 - Black PVC Jacket (UV resistant) ext. Ø 6.5mm IP67 | CA/LTWB06BFnn nn = 01 (1 mt.) 05 (5 mt.) 10 (10 mt.) |
| CN2 | Pin: Pinout: Conductors: Cable: Waterproof rate: | 12 position 1 - Brown, 2 - Blue, 3 - White, 4 - Green, 5 - Yellow, 6 - Grey, 7 - Pink, 8 - Red, 9 - Black, 10 - Orange, 11 - Purple, 12 - Green/White. UL2464 - Black PVC Jacket (UV resistant) ext. Ø 6.5mm IP67 | CA/LTWBU12BFnn nn = 01 (1 mt.) 05 (5 mt.) 10 (10 mt.) |
| CN3 | Pin: Pinout: Conductors: Cable: Waterproof rate: | 5 position 1 - Brown, 2 - White, 3 - Blue, 4 - Black, 5 - Green or Gray. UL2464 - Black PVC Jacket (UV resistant) ext. Ø 6.0mm IP68 | CA/LTW1205BFnn nn = 01 (1 mt.) 05 (5 mt.) 10 (10 mt.) |
| CN4 | Pin: Pinout: Conductors: Cable: Waterproof rate: | 5 position 1 - Brown, 2 - White, 3 - Blue, 4 - Black, 5 - Green or Gray. UL2464 - Black PVC Jacket (UV resistant) ext. Ø 6.0mm IP68 | CA/LTW1205BMnn nn = 01 (1 mt.) 05 (5 mt.) 10 (10 mt.) |
| CN5 | Pin: Pinout: Conductors: Cable: Waterproof rate: | 4 position 1 - Brown, 2 - White, 3 - Blue, 4 - Black. UL2464 - Black PVC Jacket (UV resistant) ext. Ø 6.0mm IP68 | CA/LTW0804BFnn nn = 01 (1 mt.) 05 (5 mt.) 10 (10 mt.) |

Section of the cables

| Function | Cable | |
|-------------------------|---|-----------------------------|
| | Minimum | Maximum |
| Power supply | 0.5 mm ² (AWG20) | 2.5 mm ² (AWG12) |
| Communication interface | 0.25 mm ² (AWG23) CANbus CIA-CANopen | |
| Digital inputs | 0.14 mm ² (AWG25) | 0.5 mm ² (AWG20) |
| Digital outputs | 0.14 mm ² (AWG25) | 0.5 mm ² (AWG20) |

Verify the installation

- Check all connection: power supply and inputs/outputs.
- Make sure all settings right for the application.
- Make sure the power supply is suitable for the drive.
- If possible, remove the load from the motor shaft to avoid that wrong movements cause damage.
- Enable the current to the motor and verify the applied torque.
- Enable a movement of some steps and verify if the rotation direction is the desired one.
- Disconnect the power supply, connect the load on the motor and check the full functionality.

Analysis of malfunctions



When one of the following situations occur, the drive doesn't function correctly and it is reported an error.

| DEFECT | CAUSE | ACTION |
|--|---|---|
| The external fuse to the drive burns. | May be due to a wrong connection of the power supply. | Adjust the connection and recover the fuse. Use a fuse suitable for the application. |
| Over temperature protection. | May be due to a duty cycle. | Increase the air flux and if it is possible chose a motor with higher torque at same current value. |
| Over current protection. | May be due to a short circuit on the motor power stage. | Shut down the power supply and check if the motor is damaged. |
| Noisy motor movement with vibrations. | May be caused due to a state of resonance. | Increase the resolution of the step angle and/or change the motor velocity to avoid resonance area. |
| The motor produce torque but doesn't rotate. | May be caused due to a wrong connection of the I/O's. | Check the connection of the I/O's. |

Ever Motion Solutions

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